



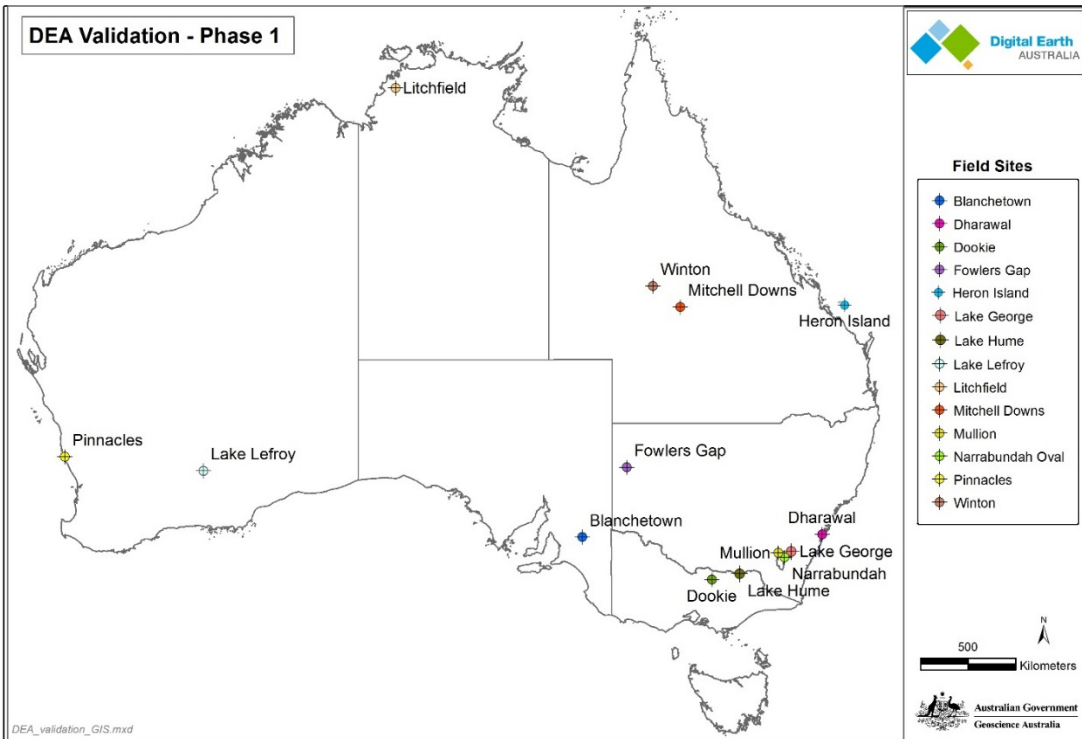
Past and Future Validation of Landsat 8 and Sentinel 2 Products, using a Drone- Based Approach

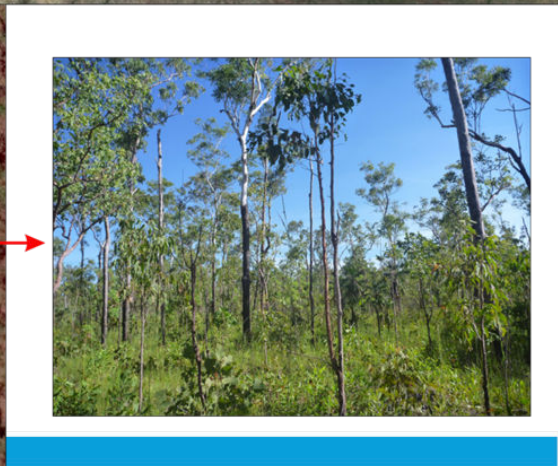
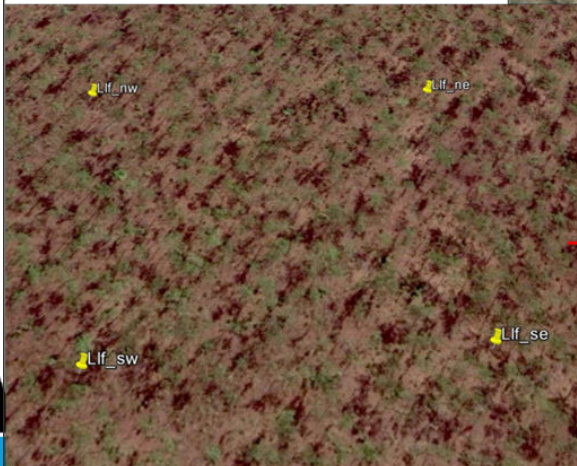
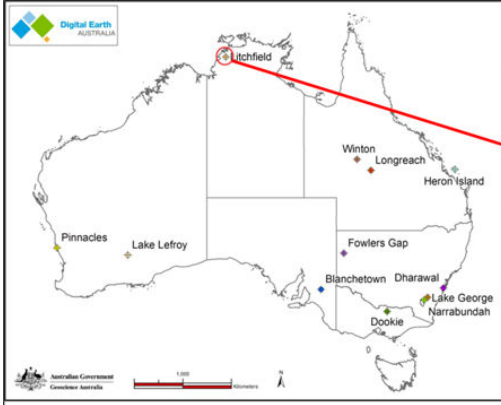
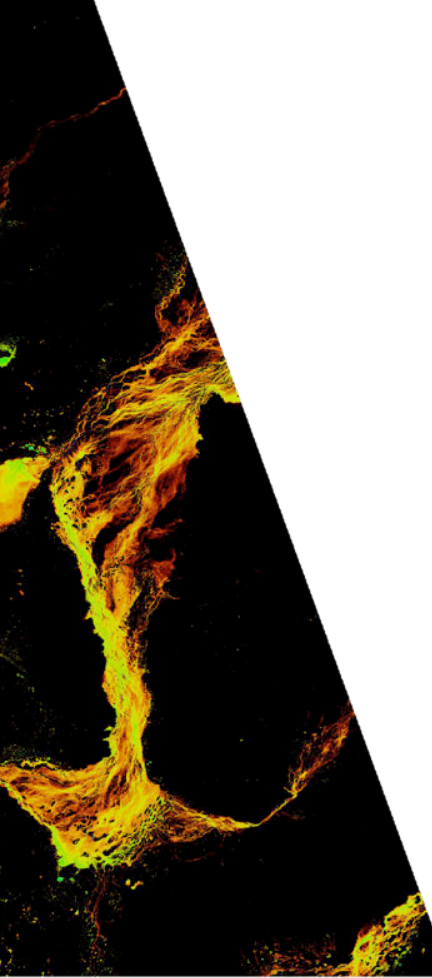
Dr Andrew Walsh
Mr Guy Byrne
Dr Mark Broomhall
Mr Medhavy Thankappan

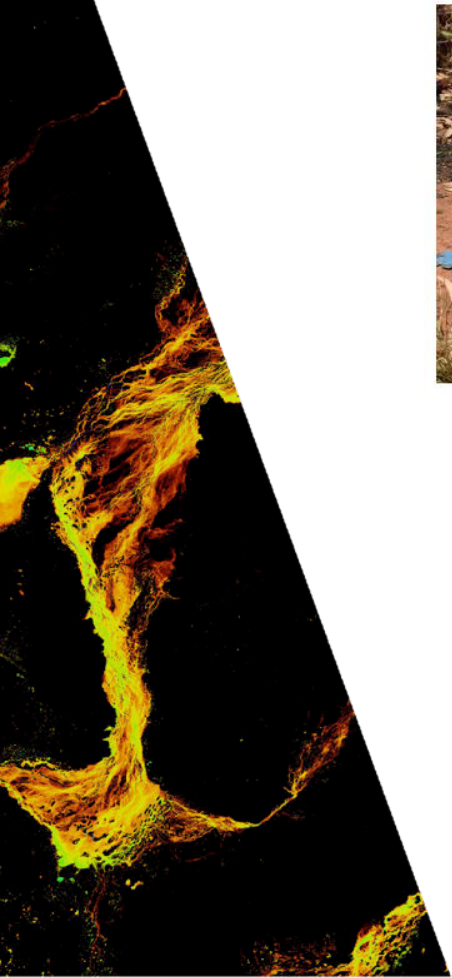
Geoscience Australia

With thanks to Dr Stefan Maier (Maitec)

DEA Validation - Phase 1





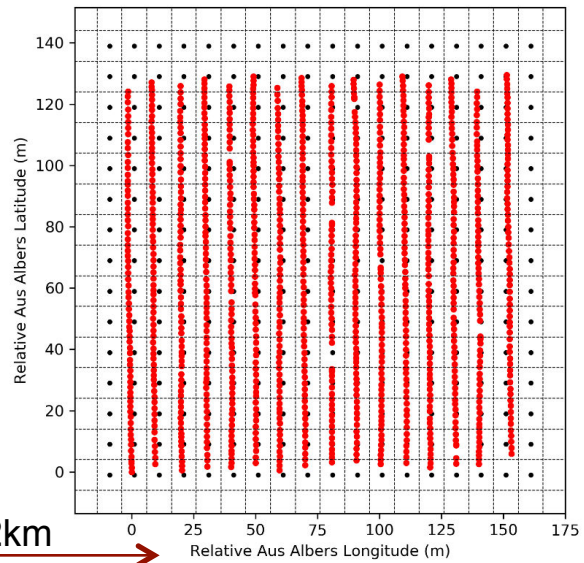
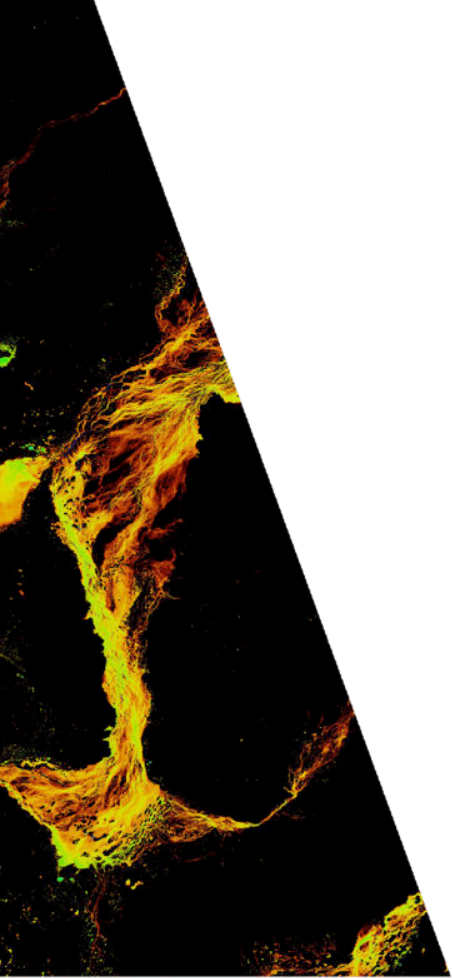


Spectroradiometer:

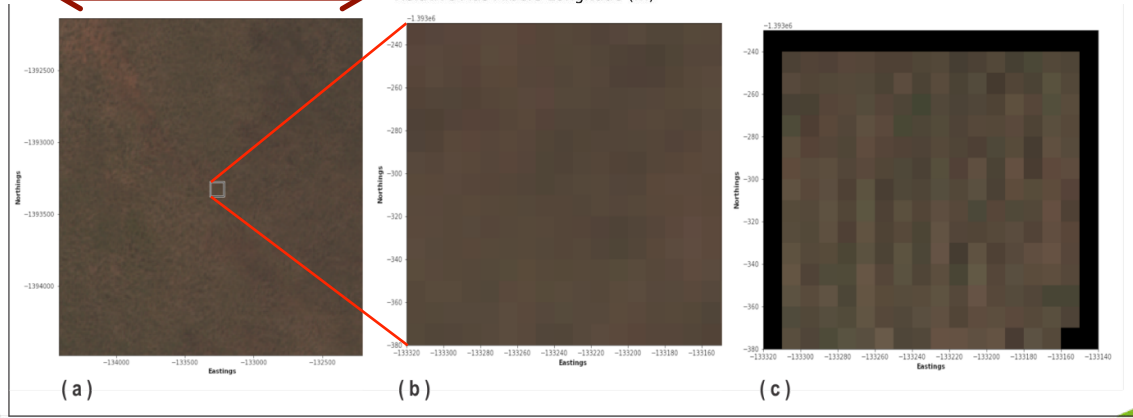
- STS-VIS from Ocean Optics mounted on a Solo UAV from 3D Robotics
- Captures spectra in 1024 channels from 337 nm to 823 nm
- 15° field-of-view

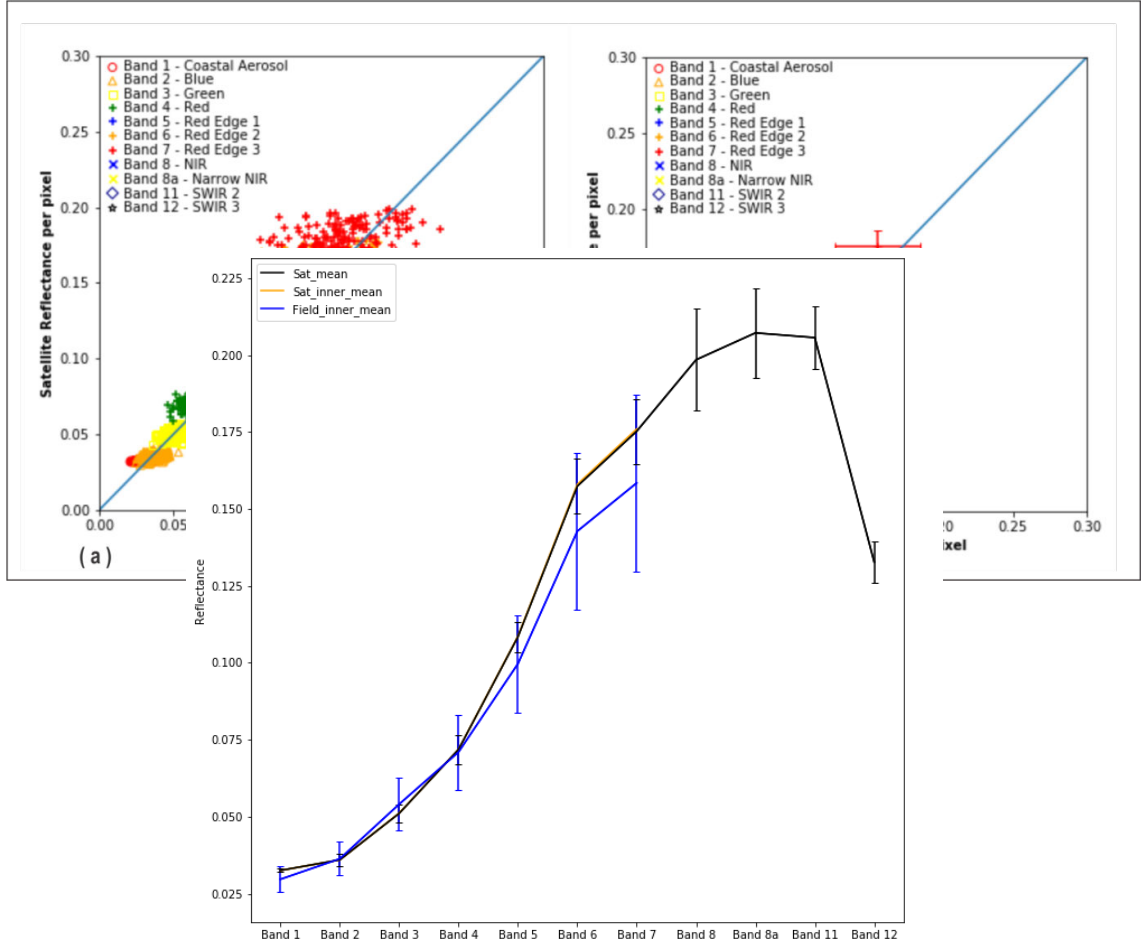
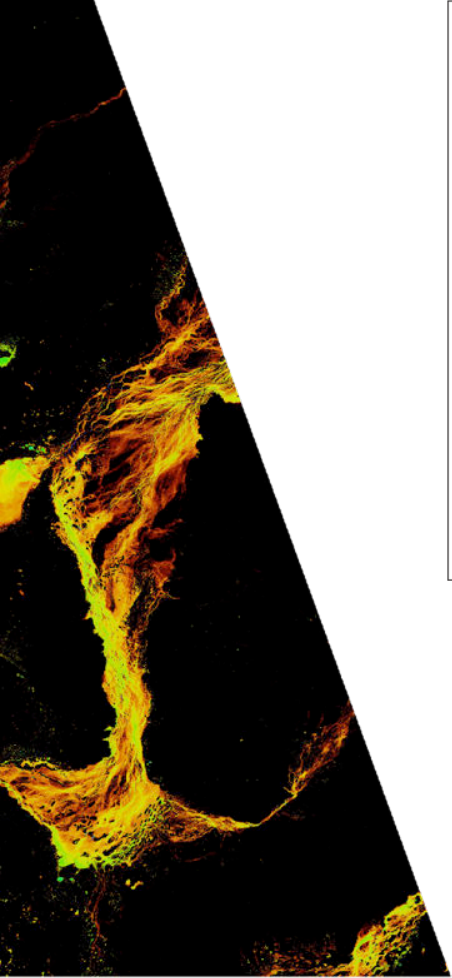
Flight Pattern:

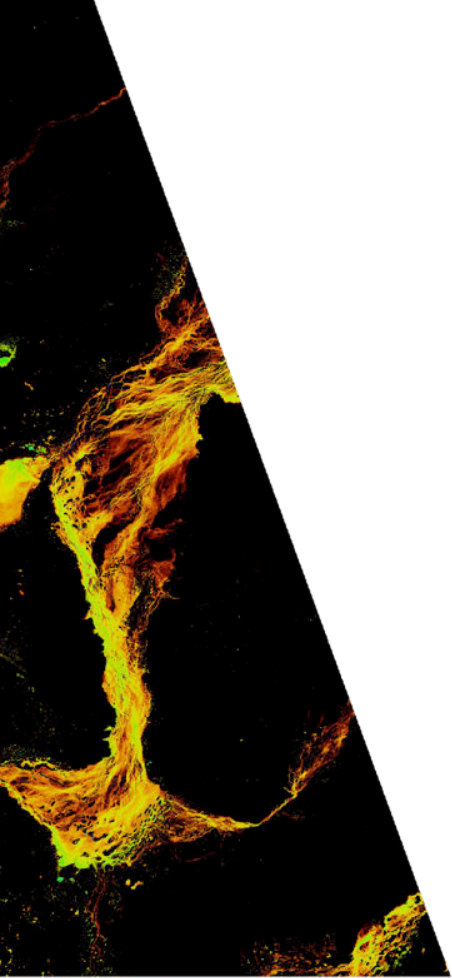
- 16 transects of 150m length with a spacing of 10m
- Nominal height of 50m
- 13m ground footprint
- Duration 7m 40s



2km







Advantages of drone over manual validation

- Quicker
- Cheaper
- Larger area
- More data
- Above canopy view

Advantages of manual over drone validation

- Full spectral range 350-2500nm
- Established procedures and equipment

Phase 2 Validation with drones

Equipment

- Matrice 600 Pro as platform (The Skyhook)
- Ocean Optics Flame spectrometer (350-1000nm)
- Ronin MX Gimbal
- Gershun tube (change field-of-view)

Training

- Remote Pilot Licence (RPL 25kg class)
- Remote Operator Certificate (ReOC)



Phase 2 Validation with drones

Motivation

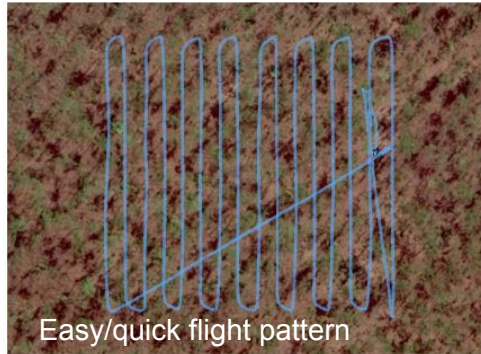
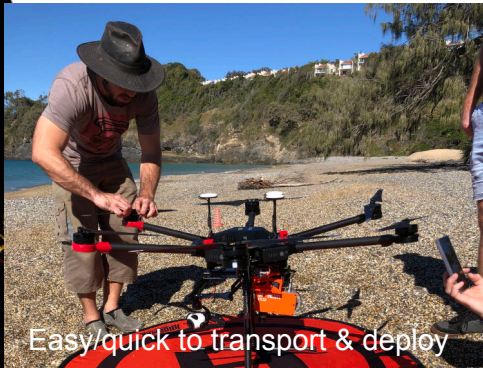
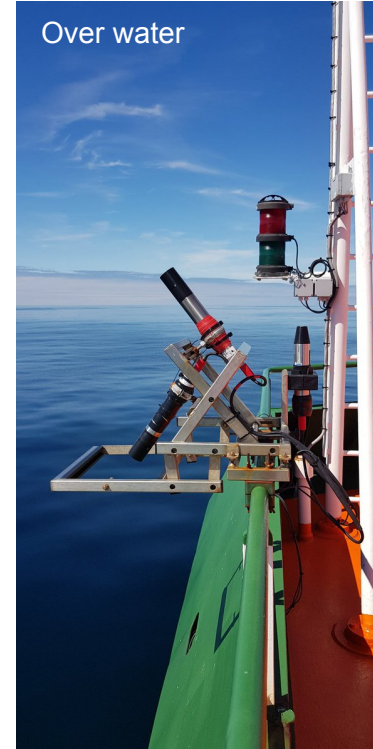
Terrain and targets

- Can fly over anything that is less than 120 m above the surface
- Anything with a steep slope (hill)
- Over water without the need for a boat

Methodology

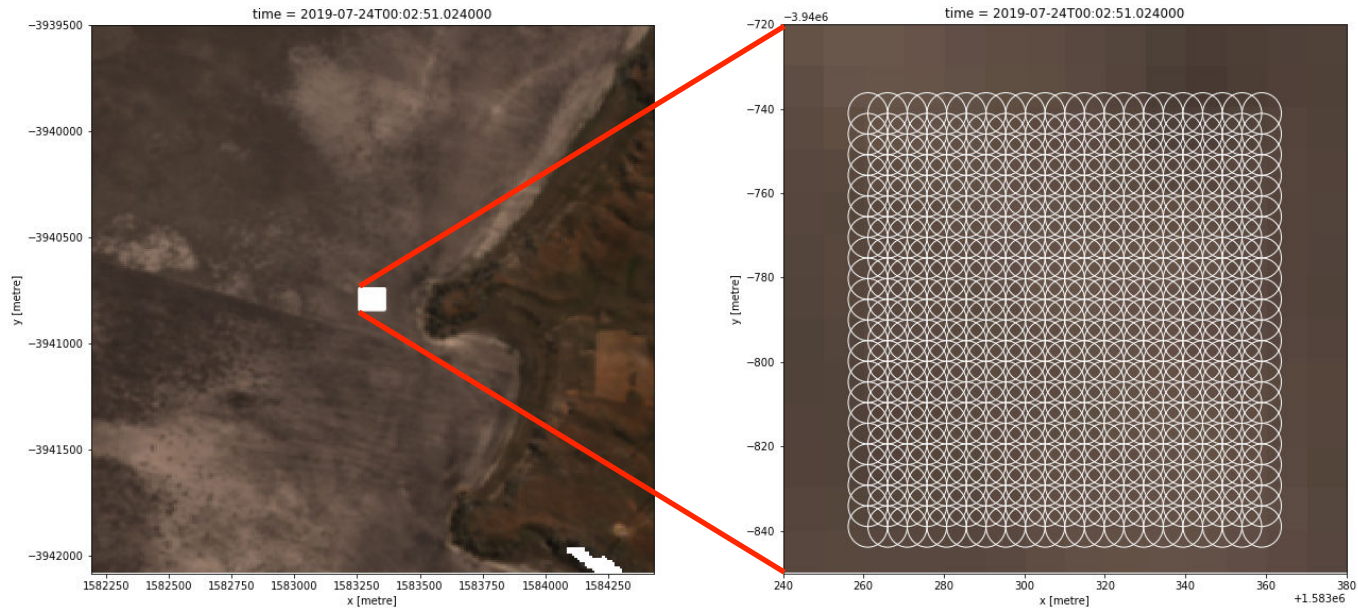
- Quick deployment and flight pattern
- Sample entire surface

Phase 2 Validation with drones



Phase 2 Validation with drones

Sample the entire surface

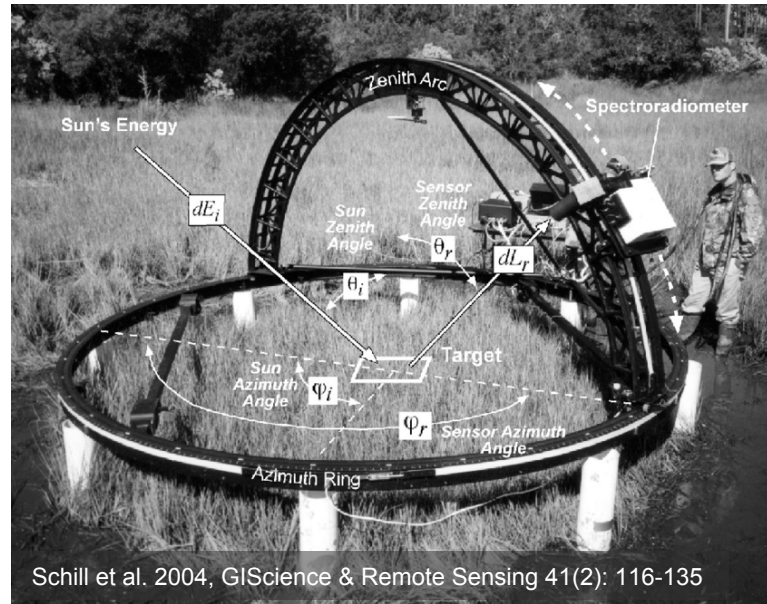


Bidirectional Reflectance Distribution Function (BRDF)



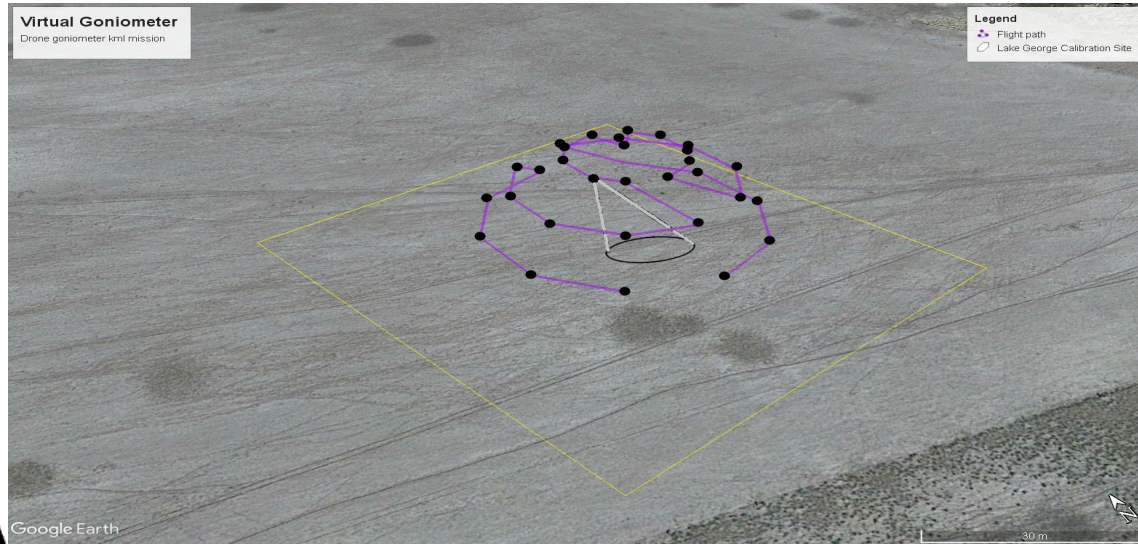
Bidirectional Reflectance Distribution Function (BRDF)

- Complex measurements – The Bidirectional Reflectance Distribution function (BRDF) can only be determined by viewing at numerous Solar, view and azimuth angles. A drone platform with a gimbal is ideal for this.



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Summary

Phase 1: Litchfield site validated successfully
→ quick, cheap, but only shorter wavelengths

Phase 2: Acquiring new equipment, developing new methods
→ Greatly increase capability to validate more sites

